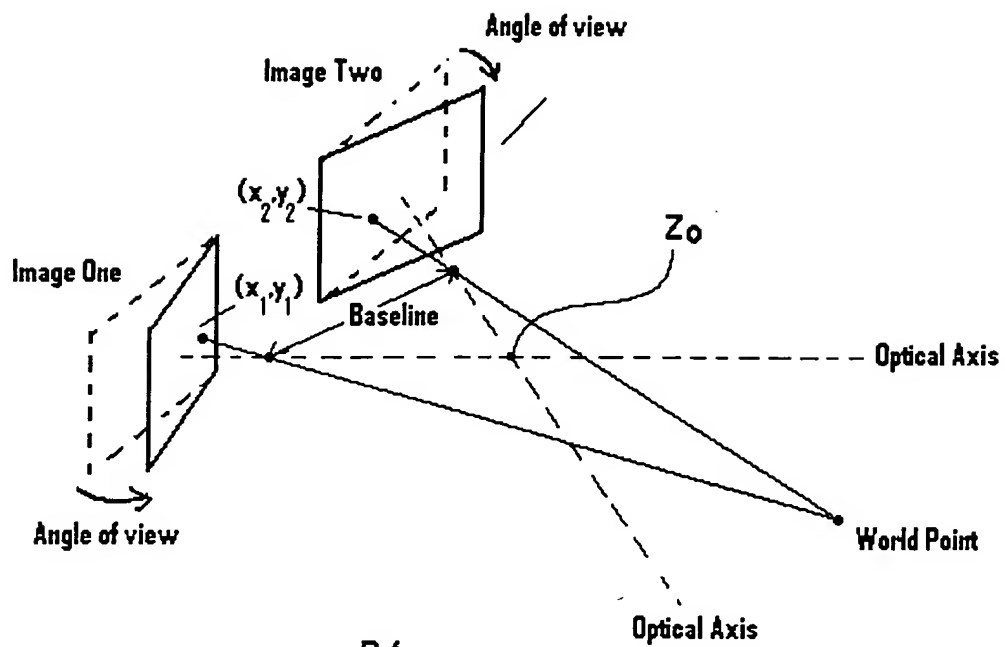


FIGURE 1A



$$\text{depth} \approx \frac{B \cdot f}{(x_1 - x_2) + \frac{B \cdot f}{Z_0}}$$

Z_0 is the distance from a world point to the image plane, when disparity for that point is equal to zero

Convergent System (concurrent optical axes)

FIGURE 1B

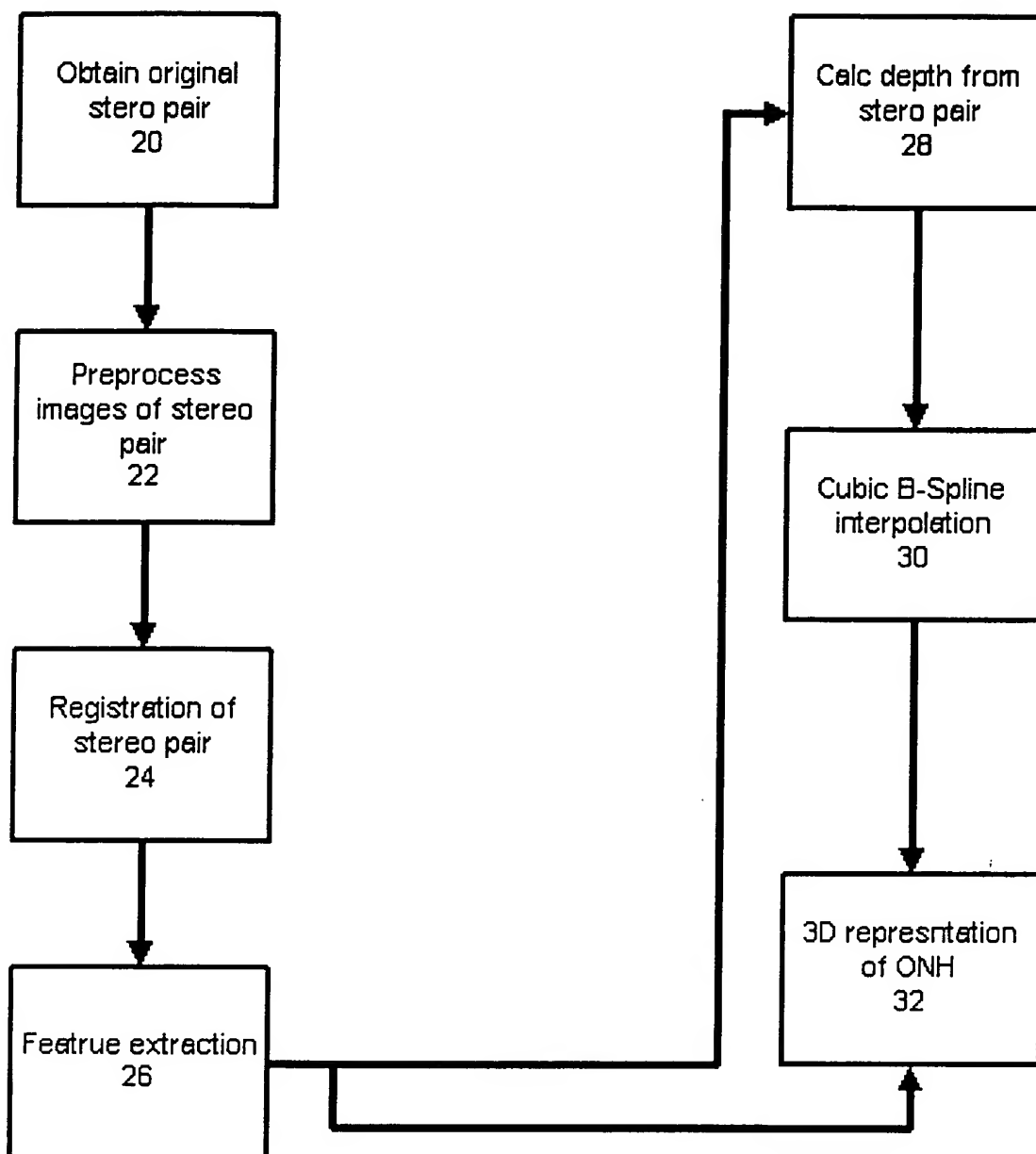


Figure 2

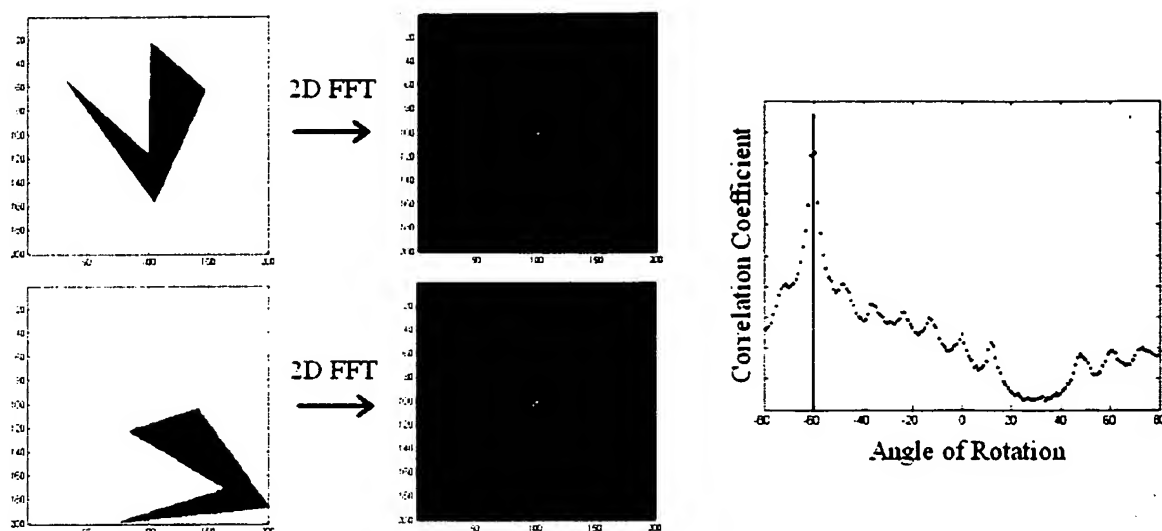


FIGURE 3

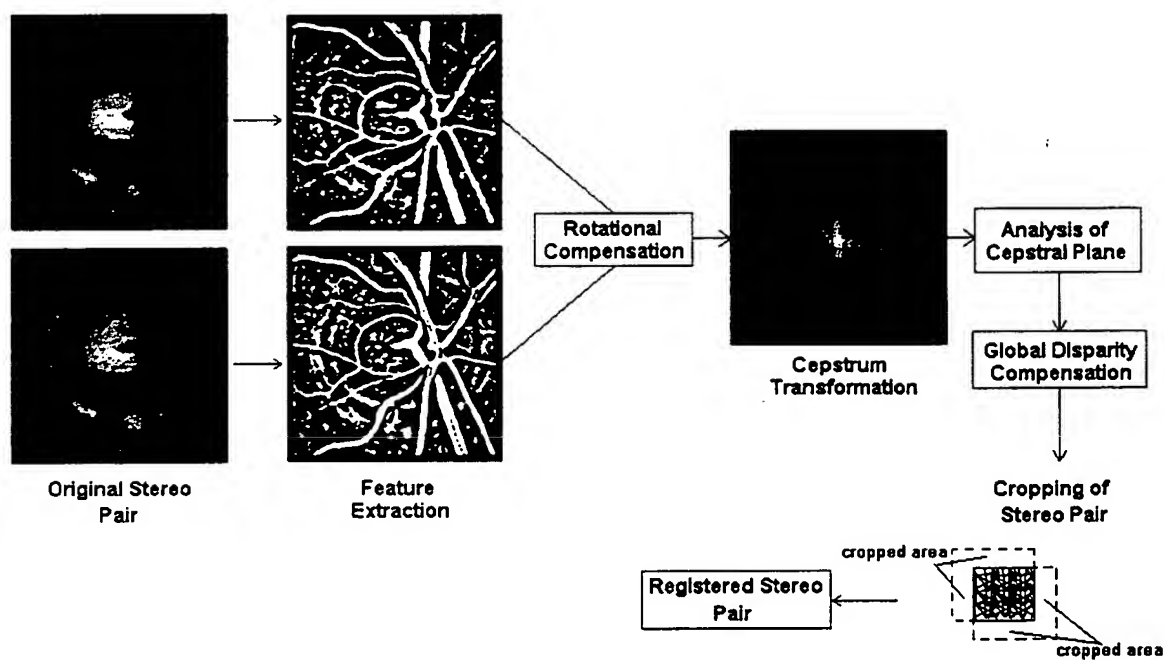
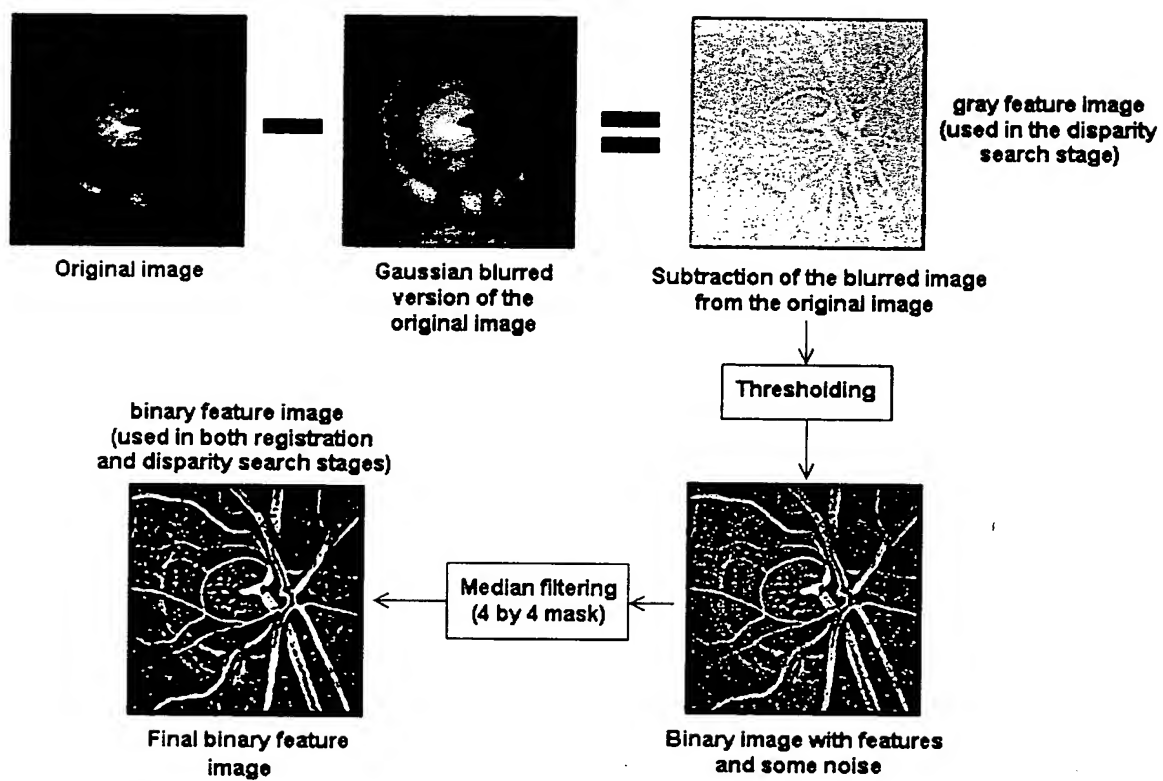


FIGURE 4

FIGURE 5



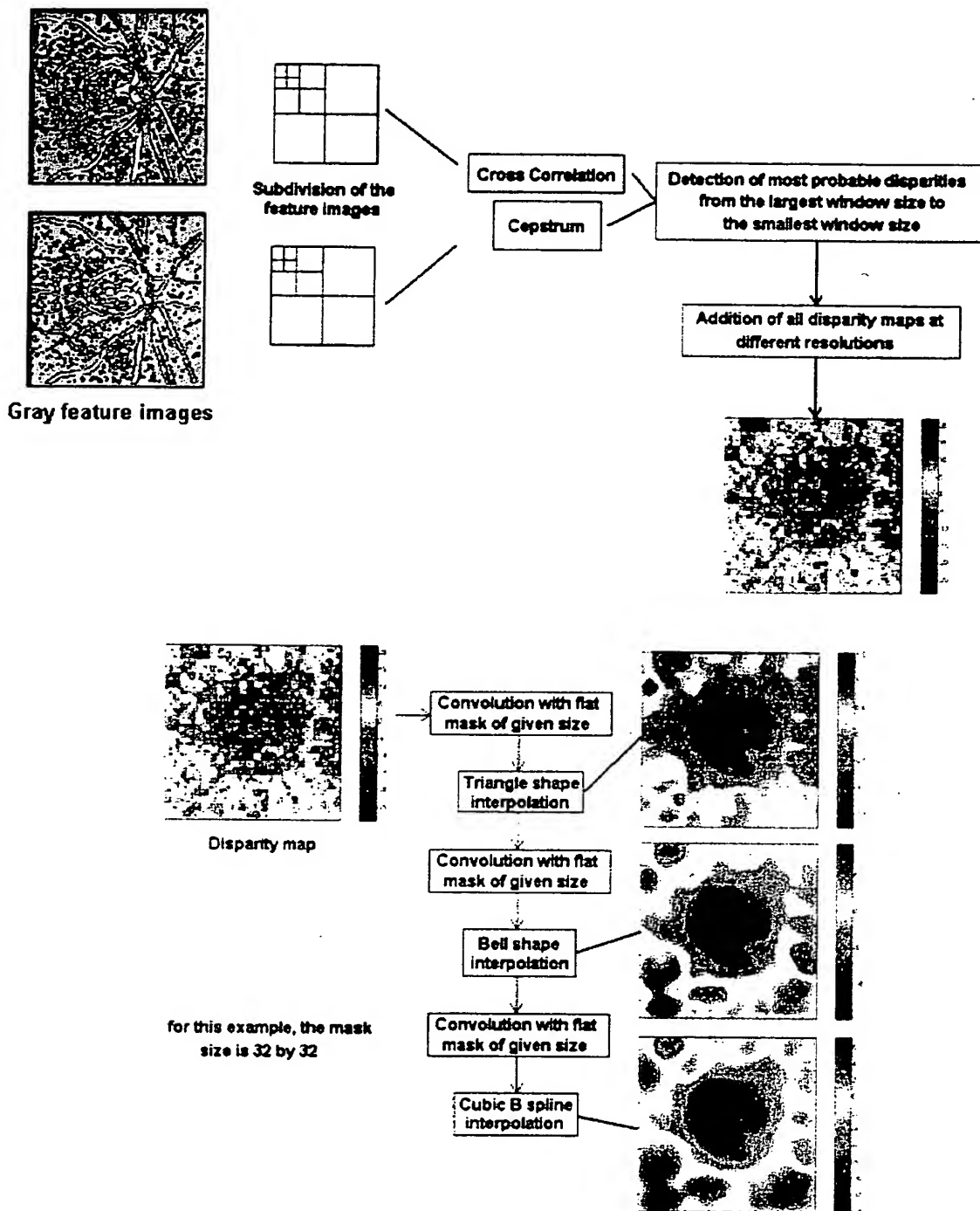
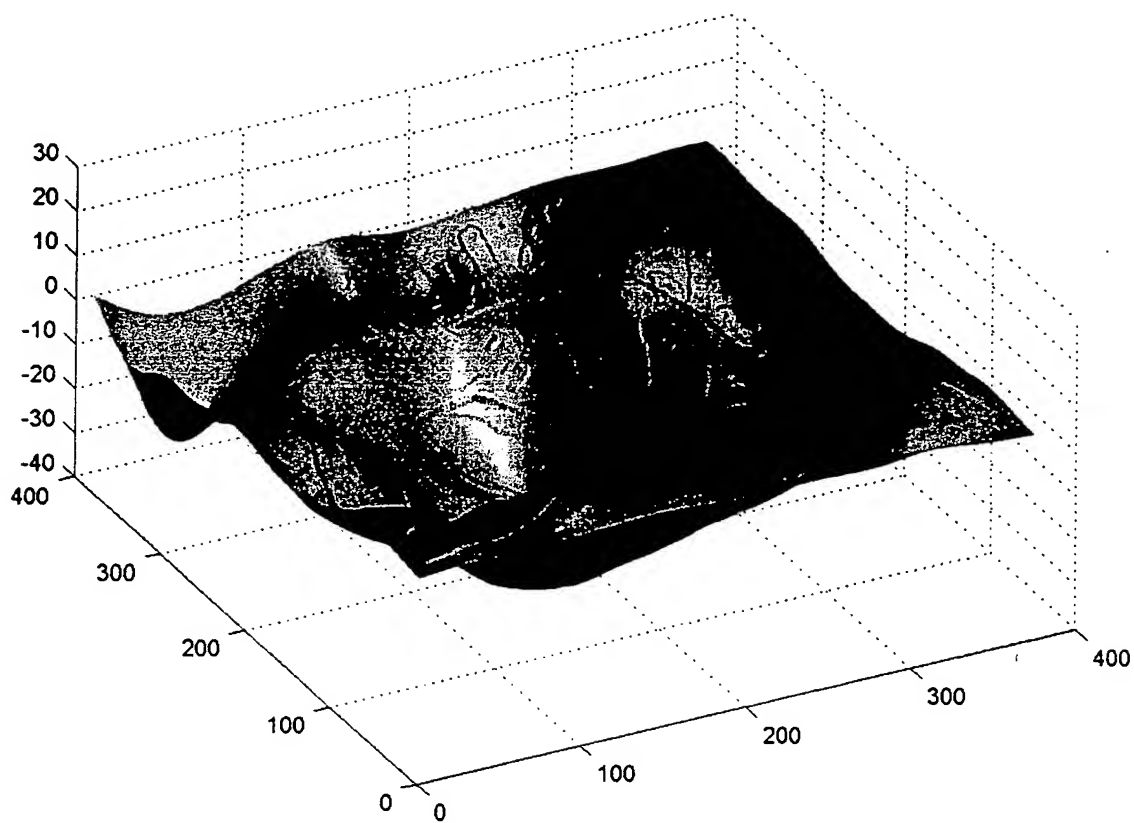


FIGURE 6



FIGURE 7



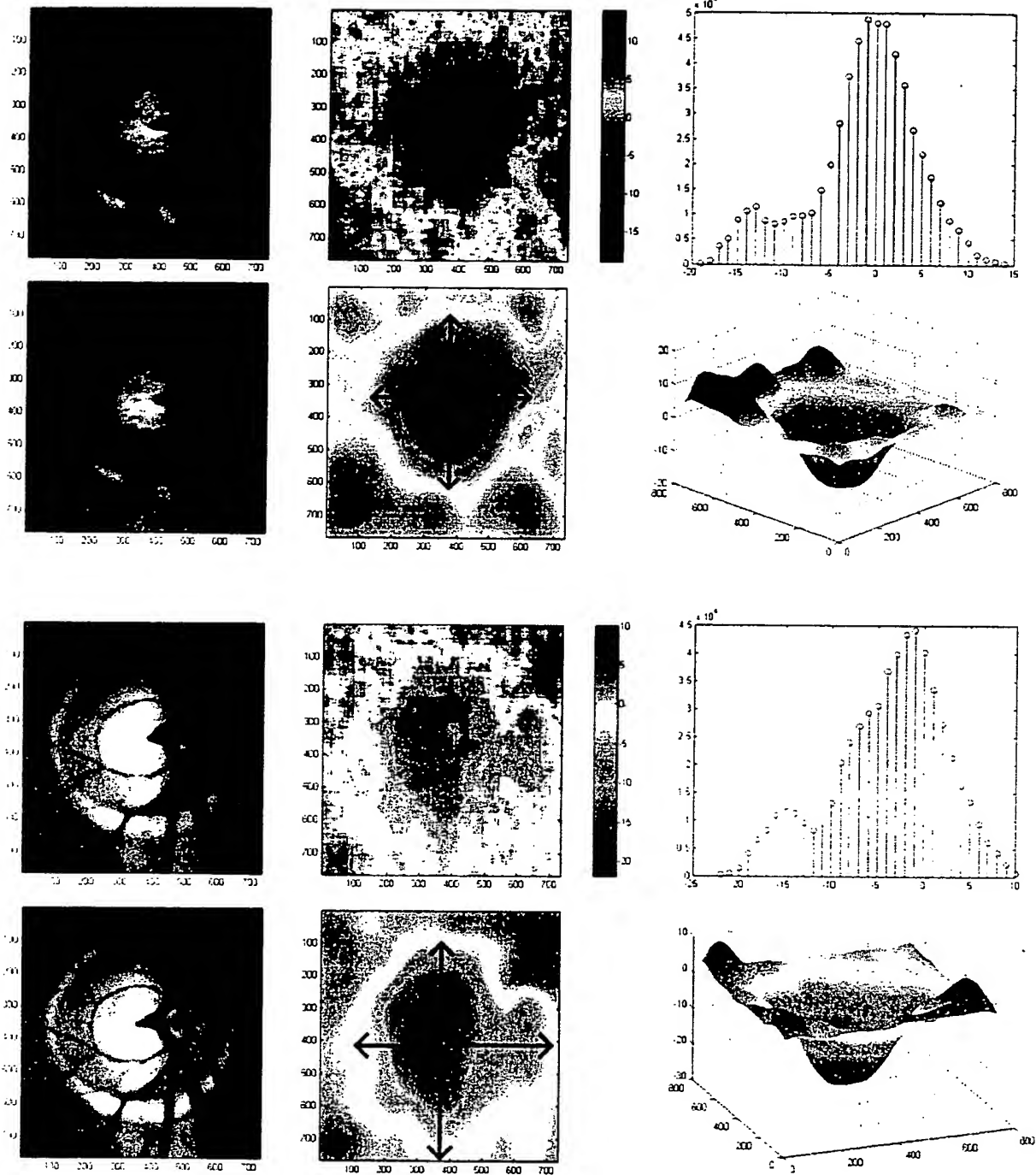


FIGURE 8

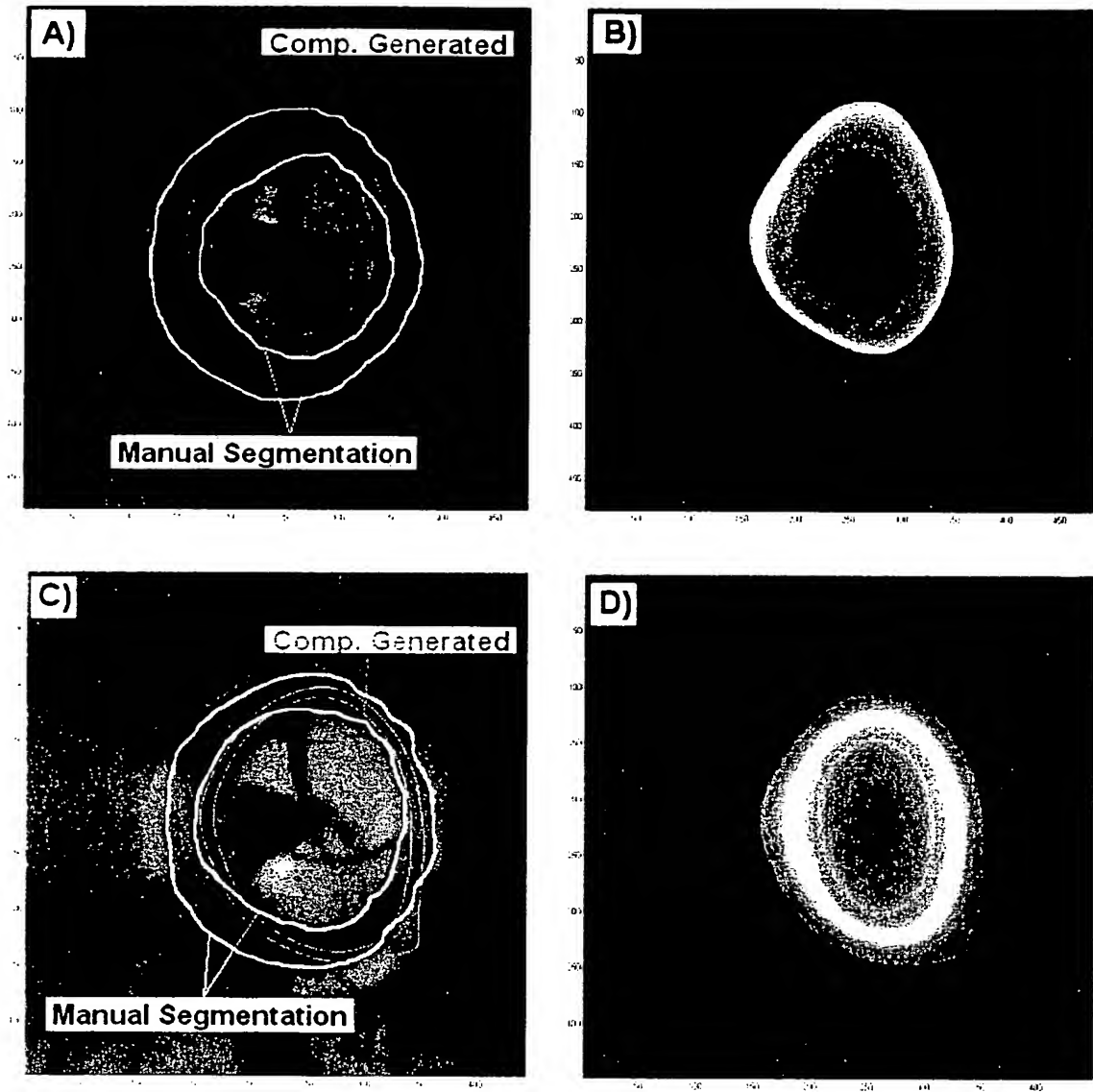


FIGURE 9

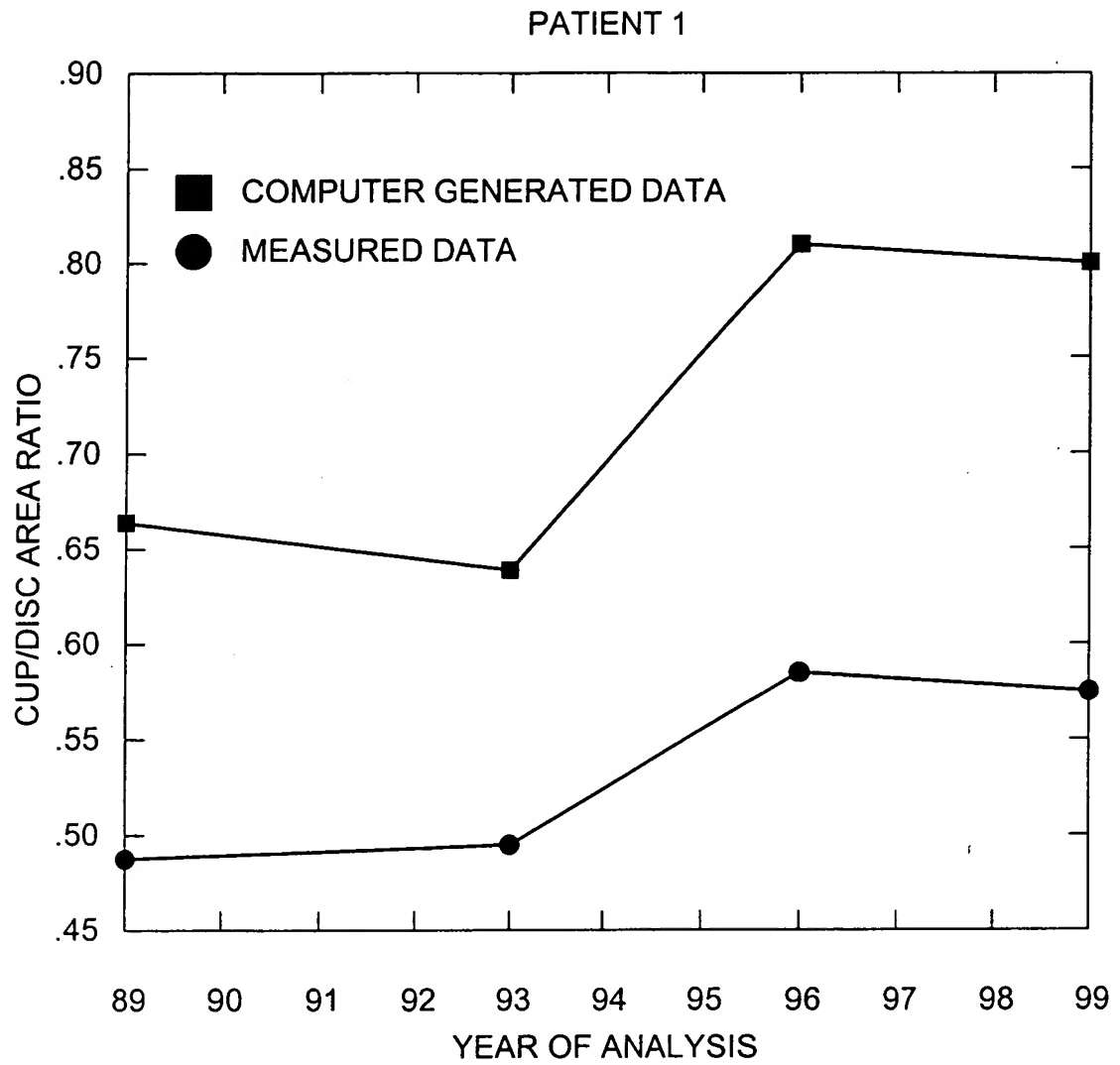


FIGURE 10A

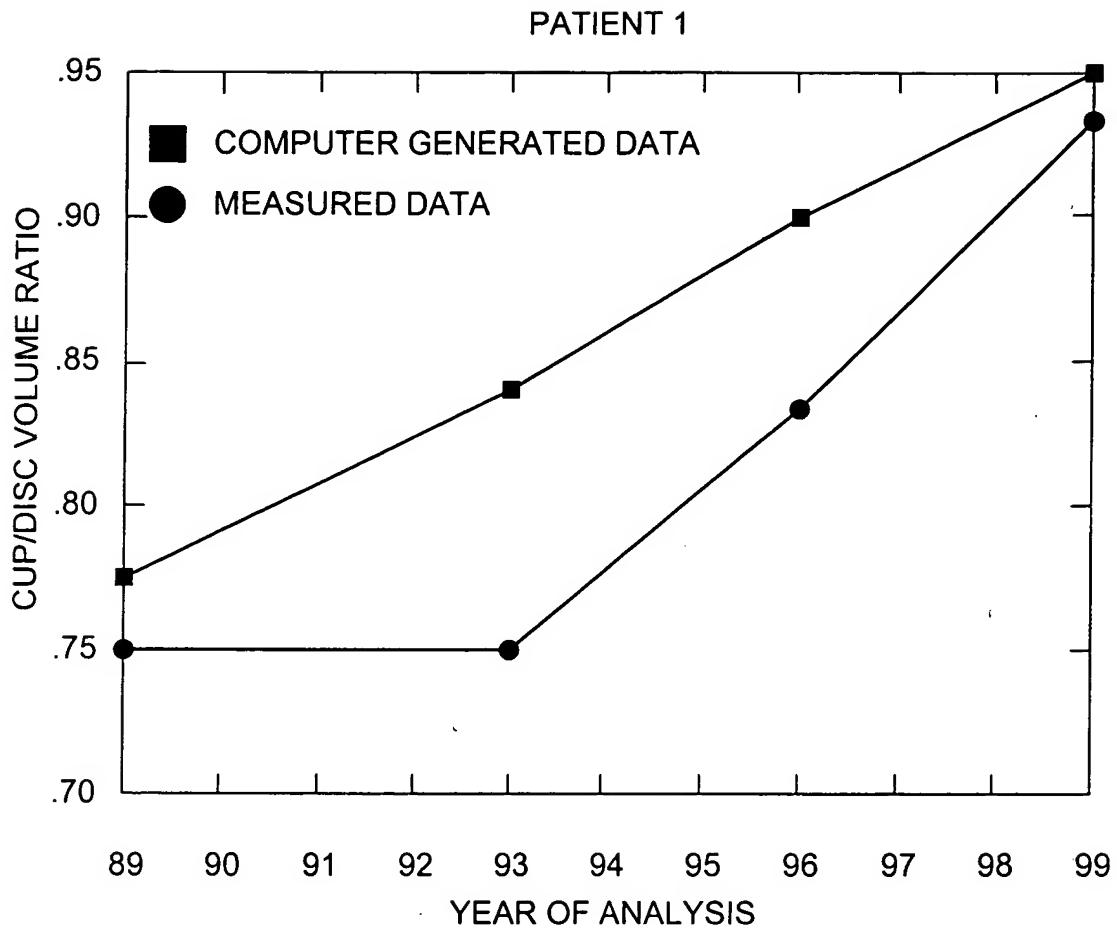
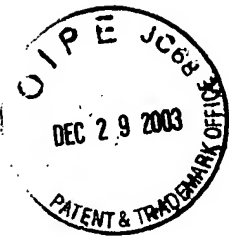


FIGURE 10B

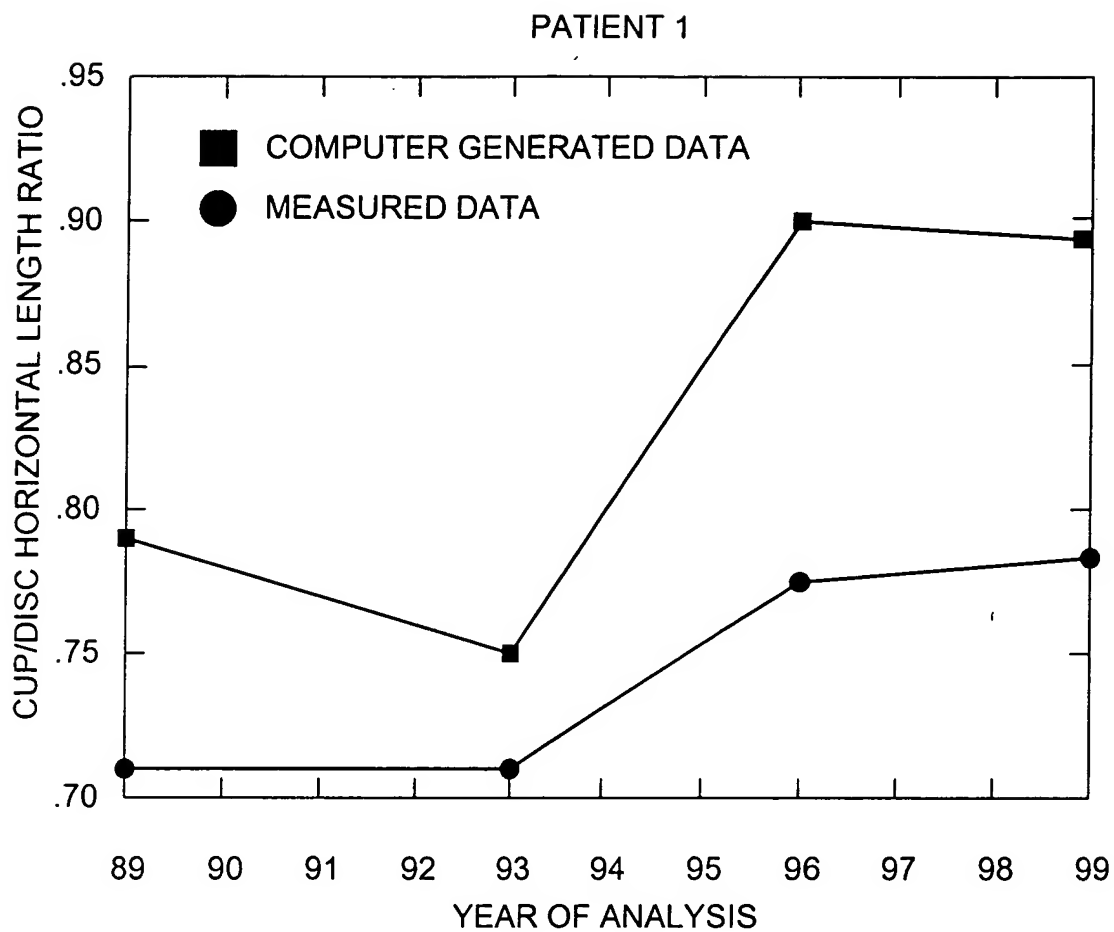


FIGURE 10C



PATIENT 1

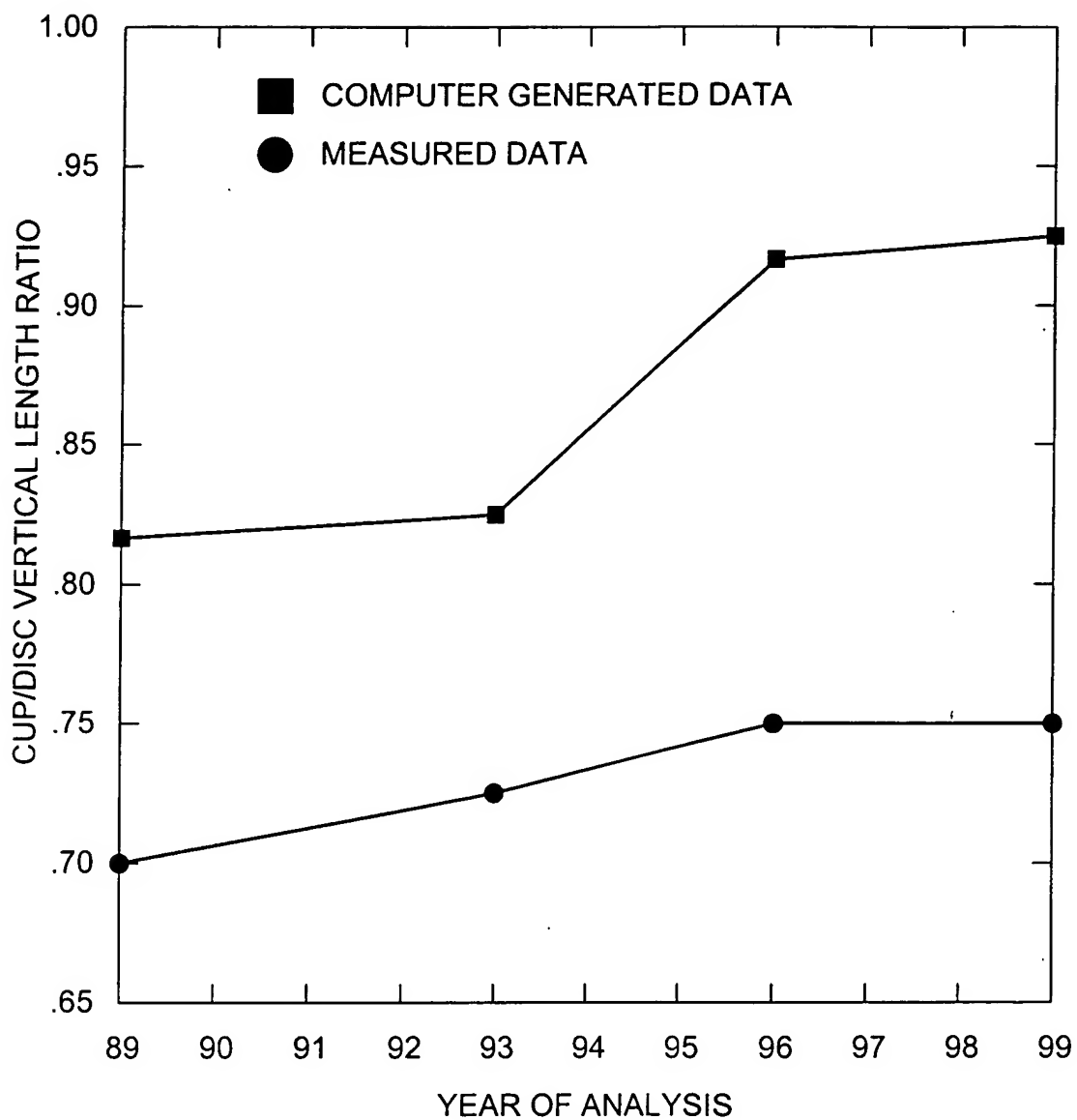


FIGURE 10D